

Large-magnetic field regimes & asymptotic preserving schemes

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Jointly with **Francis Filbet** (Toulouse 3, I.U.F.).

Parts also with **Hamed Zakerzadeh** (Toulouse 3).

Context.

In **plasma** dynamics forced by **strong magnetic fields**, coexist

- **strong oscillations** ensuring confinement of energetic particles;
- a **slow dynamics uncoupled** at leading order.

Goal: **prove** the above claim and design suitable **numerical schemes**.

This is the so-called **gyrokinetic** theory.

State of the art of the analytic theory (even now):

- either **geometrically trivial** PDEs; (St-Raymond, Miot, Bostan)
- or **linear** PDEs. (Frénod-Lutz, Possaner)

Outline.

- 1 Elements of gyrokinetics
 - Mechanism
 - Uniform magnetic fields
 - PDE counterparts
 - Two-dimensional fields
 - Three-dimensional fields
- 2 A few asymptotic preserving schemes
- 3 Conclusion

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- 1 Elements of gyrokinetics
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A dumb example.

$$(\mathbf{x}^\varepsilon, \mathbf{v}^\varepsilon) : \mathbf{R} \rightarrow \mathbf{R}^2 \times \mathbf{R}^2.$$

$$\frac{d\mathbf{x}^\varepsilon}{dt}(t) = \mathbf{v}^\varepsilon(t), \quad \frac{d\mathbf{v}^\varepsilon}{dt}(t) = -\frac{1}{\varepsilon}(\mathbf{v}^\varepsilon(t))^\perp.$$

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Short-time uniform bounds

$$\|\mathbf{v}^\varepsilon(t)\| = \|\mathbf{v}^\varepsilon(0)\|, \quad \|\mathbf{x}^\varepsilon(t)\| \leq \|\mathbf{x}^\varepsilon(0)\| + |t| \|\mathbf{v}^\varepsilon(0)\|.$$

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Uncoupling \mathbf{x}^ε from \mathbf{v}^ε

$$\mathbf{v}^\varepsilon(t) = \frac{d}{dt} \left(\varepsilon(\mathbf{v}^\varepsilon)^\perp \right) (t), \quad \frac{d}{dt} \left(\mathbf{x}^\varepsilon - \varepsilon(\mathbf{v}^\varepsilon)^\perp \right) (t) = 0.$$

Thus

$$\|\mathbf{x}^\varepsilon(t) - \mathbf{x}^\varepsilon(0)\| \leq 2\varepsilon \|\mathbf{v}^\varepsilon(0)\|.$$

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$$(\mathbf{x}^\varepsilon, \mathbf{v}^\varepsilon) : \mathbb{R} \rightarrow \mathbb{R}^2 \times \mathbb{R}^2.$$

$$\frac{d\mathbf{x}^\varepsilon}{dt}(t) = \mathbf{v}^\varepsilon(t), \quad \frac{d\mathbf{v}^\varepsilon}{dt}(t) = -\frac{1}{\varepsilon}(\mathbf{v}^\varepsilon(t))^\perp.$$

Improved uniform bounds

$$\|\mathbf{v}^\varepsilon(t)\| = \|\mathbf{v}^\varepsilon(0)\|, \quad \|\mathbf{x}^\varepsilon(t)\| \leq \|\mathbf{x}^\varepsilon(0)\| + \min(\{|t|, 2\varepsilon\}) \|\mathbf{v}^\varepsilon(0)\|.$$

Uncoupling \mathbf{x}^ε from \mathbf{v}^ε

$$\mathbf{v}^\varepsilon(t) = \frac{d}{dt} \left(\varepsilon(\mathbf{v}^\varepsilon)^\perp \right) (t), \quad \frac{d}{dt} \left(\mathbf{x}^\varepsilon - \varepsilon(\mathbf{v}^\varepsilon)^\perp \right) (t) = 0.$$

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Uniform magnetic fields, transverse dynamics.

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Short-time uniform bounds.

$$\|\mathbf{v}^\varepsilon(t)\| \leq \|\mathbf{v}^\varepsilon(0)\| + 2|t| \|\mathbf{E}^\varepsilon\|_{L^\infty},$$

$$\|\mathbf{x}^\varepsilon(t)\| \leq \|\mathbf{x}^\varepsilon(0)\| + |t| \|\mathbf{v}^\varepsilon(0)\| + t^2 \|\mathbf{E}^\varepsilon\|_{L^\infty}.$$

$$\begin{aligned} \mathbf{v}^\varepsilon(t) &= \frac{d}{dt} \left(\varepsilon(\mathbf{v}^\varepsilon)^\perp \right) (t) - \varepsilon(\mathbf{E}^\varepsilon)^\perp(t, \mathbf{x}^\varepsilon(t)), \\ \frac{d}{dt} \left(\mathbf{x}^\varepsilon - \varepsilon(\mathbf{v}^\varepsilon)^\perp \right) (t) &= -\varepsilon(\mathbf{E}^\varepsilon)^\perp(t, \mathbf{x}^\varepsilon(t)). \end{aligned}$$

Thus

$$\|\mathbf{x}^\varepsilon(t) - \mathbf{x}^\varepsilon(0)\| \leq \varepsilon (2 \|\mathbf{v}^\varepsilon(0)\| + 3|t| \|\mathbf{E}^\varepsilon\|_{L^\infty}).$$

Uniform magnetic fields, second order.

Guiding center variable

$$\mathbf{x}_{\text{gc}}^\varepsilon := \mathbf{x}^\varepsilon - \varepsilon(\mathbf{v}^\varepsilon)^\perp$$

so that

$$\frac{d\mathbf{x}_{\text{gc}}^\varepsilon}{dt}(t) = -\varepsilon(\mathbf{E}^\varepsilon)^\perp(t, \mathbf{x}_{\text{gc}}^\varepsilon(t) + \varepsilon(\mathbf{v}^\varepsilon)^\perp).$$

Uniform magnetic fields, second order.

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Proposition

$$\|\mathbf{x}_{\text{gc}}^\varepsilon(t) - \mathbf{y}_{\text{gc}}^\varepsilon(t)\| \leq \varepsilon^2 \|\mathbf{d}_x \mathbf{E}\|_{L^\infty} e^{\varepsilon|t| \|\mathbf{d}_x \mathbf{E}\|_{L^\infty}} (t \|\mathbf{v}^\varepsilon(0)\| + t^2 \|\mathbf{E}\|_{L^\infty})$$

where $\mathbf{y}_{\text{gc}}^\varepsilon$ solves

$$\begin{aligned} \frac{d\mathbf{y}_{\text{gc}}^\varepsilon}{dt}(t) &= -\varepsilon(\mathbf{E}^\varepsilon)^\perp(t, \mathbf{y}_{\text{gc}}^\varepsilon(t)), \\ \mathbf{y}_{\text{gc}}^\varepsilon(0) &= \mathbf{x}_{\text{gc}}^\varepsilon(0). \end{aligned}$$

Large-time uniform estimates, first way.

$$\frac{dx^\varepsilon}{dt}(t) = \mathbf{v}^\varepsilon(t) \quad \frac{dv^\varepsilon}{dt}(t) = -\frac{1}{\varepsilon}(\mathbf{v}^\varepsilon(t))^\perp + \mathbf{E}^\varepsilon(t, \mathbf{x}^\varepsilon(t)).$$

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Introducing a **more purely oscillatory** variable.

$$\begin{aligned} \frac{d}{dt} \left(\mathbf{v}^\varepsilon + \varepsilon(\mathbf{E}^\varepsilon)^\perp(\cdot, \mathbf{x}^\varepsilon) \right) (t) &= -\frac{1}{\varepsilon} \left(\mathbf{v}^\varepsilon(t) + \varepsilon(\mathbf{E}^\varepsilon)^\perp(t, \mathbf{x}^\varepsilon(t)) \right)^\perp \\ &+ \varepsilon \left(\partial_t(\mathbf{E}^\varepsilon)^\perp(t, \mathbf{x}^\varepsilon(t)) + d_{\mathbf{x}}(\mathbf{E}^\varepsilon)^\perp(t, \mathbf{x}^\varepsilon(t))(\mathbf{v}^\varepsilon(t)) \right). \end{aligned}$$

Thus

$$\begin{aligned} \|\mathbf{v}^\varepsilon(t)\| &\leq e^{\varepsilon|t|} \|d_{\mathbf{x}}\mathbf{E}^\varepsilon\|_{L^\infty} \left(\|\mathbf{v}^\varepsilon(0)\| + 2\varepsilon \|\mathbf{E}^\varepsilon\|_{L^\infty} \right. \\ &\quad \left. + \varepsilon|t| (\|\partial_t\mathbf{E}^\varepsilon\|_{L^\infty} + \|d_{\mathbf{x}}\mathbf{E}^\varepsilon\|_{L^\infty} \|\mathbf{E}^\varepsilon\|_{L^\infty}) \right) \end{aligned}$$

Large-time uniform estimates, second way.

Kinetic energy variable

$$e(\mathbf{v}^\varepsilon) := \frac{1}{2} \|\mathbf{v}^\varepsilon\|^2$$

as a slow variable.

$$\frac{de(\mathbf{v}^\varepsilon)}{dt}(t) = \langle \mathbf{v}^\varepsilon, \mathbf{E}^\varepsilon(t, \mathbf{x}^\varepsilon(t)) \rangle.$$

Large-time uniform estimates, second way.

Kinetic energy variable

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as a **slow variable**.

$$\frac{de(\mathbf{v}^\varepsilon)}{dt}(t) = \langle \mathbf{v}^\varepsilon, \mathbf{E}^\varepsilon(t, \mathbf{x}^\varepsilon(t)) \rangle.$$

Introducing a **slower** variable, uncoupling e^ε from \mathbf{v}^ε .

$$\begin{aligned} & \frac{d}{dt} \left(e(\mathbf{v}^\varepsilon) - \varepsilon \langle (\mathbf{v}^\varepsilon)^\perp, \mathbf{E}^\varepsilon(\cdot, \mathbf{x}^\varepsilon) \rangle \right) (t) \\ &= -\varepsilon \left\langle (\mathbf{v}^\varepsilon)^\perp, (\partial_t \mathbf{E}^\varepsilon(t, \mathbf{x}^\varepsilon(t)) + d_x \mathbf{E}^\varepsilon(t, \mathbf{x}^\varepsilon(t))(\mathbf{v}^\varepsilon(t))) \right\rangle. \end{aligned}$$

Same kind of conclusion.

Uniform magnetic fields, large time.

$$\frac{d}{dt} \left(\mathbf{x}^\varepsilon - \varepsilon(\mathbf{v}^\varepsilon)^\perp \right) (t) = -\varepsilon(\mathbf{E}^\varepsilon)^\perp(t, \mathbf{x}^\varepsilon(t)).$$

Uniform magnetic fields, large time.

$$\frac{d}{dt} \left(\mathbf{x}^\varepsilon - \varepsilon (\mathbf{v}^\varepsilon)^\perp \right) (t) = -\varepsilon (\mathbf{E}^\varepsilon)^\perp (t, \mathbf{x}^\varepsilon(t)).$$

Proposition

$$\begin{aligned} \|\mathbf{x}^\varepsilon(t) - \mathbf{y}^\varepsilon(t)\| &\leq \varepsilon e^{2\varepsilon|t|} \|\mathbf{d}_x \mathbf{E}^\varepsilon\|_{L^\infty} \left(2(\|\mathbf{v}^\varepsilon(0)\| + \varepsilon \|\mathbf{E}^\varepsilon\|_{L^\infty}) \right. \\ &\quad \left. + \varepsilon |t| (\|\partial_t \mathbf{E}^\varepsilon\|_{L^\infty} + \|\mathbf{d}_x \mathbf{E}^\varepsilon\|_{L^\infty} \|\mathbf{E}^\varepsilon\|_{L^\infty}) \right) \end{aligned}$$

where \mathbf{y}^ε solves

$$\begin{aligned} \frac{d\mathbf{y}^\varepsilon}{dt}(t) &= -\varepsilon (\mathbf{E}^\varepsilon)^\perp(t, \mathbf{y}^\varepsilon(t)), \\ \mathbf{y}^\varepsilon(0) &= \mathbf{x}^\varepsilon(0). \end{aligned}$$

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From nonlinear ODEs...

Let Φ and Φ_{slow} be **flows** associated with respective ODEs

$$\frac{d\mathbf{X}}{dt}(t) = \mathcal{X}(t, \mathbf{X}(t)) \quad \text{and} \quad \frac{d\mathbf{a}}{dt}(t) = \mathcal{X}_{\text{slow}}(t, \mathbf{a}(t))$$

and \mathcal{A} and \mathcal{M} be **slow maps** and **weights** such that, for a.e. $t \geq 0$,

$$\|\mathcal{A}(t, \Phi(t, 0, \mathbf{X}_0)) - \Phi_{\text{slow}}(t, 0, \mathcal{A}(0, \mathbf{X}_0))\| \leq \mathcal{M}(t, \mathbf{X}_0).$$

...to linear PDEs.

Then if f solves

$$\partial_t f + \operatorname{div}_{\mathbf{x}}(\mathcal{X} f) = 0, \quad f(0, \cdot) = f_0,$$

and $F(t, \cdot) = \mathcal{A}(t, \cdot)_* f(t, \cdot)$ is the push-forward of f by the slow map \mathcal{A} then for a.e. $t \geq 0$

$$\|F(t, \cdot) - G(t, \cdot)\|_{\dot{W}^{-1,1}} \leq \int \mathcal{M}(t, \cdot) d|f_0|$$

where G solves

$$\partial_t G + \operatorname{div}_{\mathbf{a}}(\mathcal{X}_{\text{as}} G) = 0, \quad G(0, \cdot) = \mathcal{A}(0, \cdot)_* f_0.$$

Pushing forward and averaging.

Definition: dual to composition, $\langle \mathcal{A}_* \mu, \varphi \rangle := \langle \mu, \varphi \circ \mathcal{A} \rangle$.

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Pushing by **characteristic flow** (from 0 to t):

$$\partial_t f + \operatorname{div}_{\mathbf{x}}(\mathcal{X} f) = 0 \quad \text{solved by} \quad f(t, \cdot) = \Phi(t, 0, \cdot)_*(f(0, \cdot)).$$

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In regular cases, **averaging** over level sets

$$\mathcal{A}_*(f)(a) = \int_{\mathcal{A}^{-1}(\{a\})} f(\mathbf{X}) \frac{d\sigma_a(\mathbf{X})}{\sqrt{\det(d\mathcal{A}(\mathbf{X})(d\mathcal{A}(\mathbf{X}))^*)}}$$

where σ_a denotes the surface measure on $\mathcal{A}^{-1}(\{a\})$.

The Vlasov equation.

$$\partial_t f^\varepsilon + \operatorname{div}_{\mathbf{x}}(f^\varepsilon \mathbf{v}) + \operatorname{div}_{\mathbf{v}} \left(f^\varepsilon \left(\mathbf{E}^\varepsilon(t, \mathbf{x}) - \frac{1}{\varepsilon} \mathbf{v}^\perp \right) \right) = 0$$

Macroscopic density

$$\rho^\varepsilon(t, \cdot) := \mathcal{A}(t, \cdot)_* f^\varepsilon(t, \cdot) = \int_{\mathbb{R}^2} f^\varepsilon(t, \cdot, \mathbf{v}) \, d\mathbf{v}.$$

with $\mathcal{A}(t, (\mathbf{x}, \mathbf{v})) = \mathbf{x}$.

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Corollary

$$\|\rho^\varepsilon(t, \cdot) - F^\varepsilon(t, \cdot)\|_{\dot{W}^{-1,1}} \leq \varepsilon C_{\varepsilon, \|E^\varepsilon\|_{W^{1,\infty}}, \varepsilon t} \int (1 + \|\mathbf{v}\|) \, d|f_0|(\mathbf{x}, \mathbf{v})$$

where F^ε solves

$$\frac{\partial F^\varepsilon}{\partial t} - \varepsilon \operatorname{div}_{\mathbf{x}} \left(F^\varepsilon (\mathbf{E}^\varepsilon)^\perp \right) = 0, \quad F^\varepsilon(0, \cdot) = \rho^\varepsilon(0, \cdot).$$

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Inhomogeneous magnetic field.

$$\frac{d\mathbf{x}^\varepsilon}{dt}(t) = \mathbf{v}^\varepsilon(t)$$

$$\frac{d\mathbf{v}^\varepsilon}{dt}(t) = -\frac{B^\varepsilon(t, \mathbf{x}^\varepsilon(t))}{\varepsilon} (\mathbf{v}^\varepsilon(t))^\perp + \mathbf{E}^\varepsilon(t, \mathbf{x}^\varepsilon(t))$$

with non vanishing B^ε .

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with non vanishing B^ε .

After a first elimination,

$$\begin{aligned}\frac{d}{dt} \left(\mathbf{x}^\varepsilon - \varepsilon \frac{(\mathbf{v}^\varepsilon)^\perp}{B^\varepsilon(\cdot, \mathbf{x}^\varepsilon)} \right) (t) \\ = -\varepsilon \frac{(\mathbf{E}^\varepsilon)^\perp(t, \mathbf{x}^\varepsilon(t))}{B^\varepsilon(t, \mathbf{x}^\varepsilon(t))} - \varepsilon (\mathbf{v}^\varepsilon)^\perp (\partial_t + \mathbf{v}^\varepsilon(t) \cdot \nabla_{\mathbf{x}}) \left(\frac{1}{B^\varepsilon} \right) (t, \mathbf{x}^\varepsilon(t)).\end{aligned}$$

Quadratic term in \mathbf{v}^ε .

Back to the dumb example.

$$\frac{d\mathbf{v}^\varepsilon}{dt}(t) = -\frac{1}{\varepsilon}(\mathbf{v}^\varepsilon(t))^\perp.$$

implies for any quadratic form Q

$$\begin{aligned} Q(\mathbf{v}^\varepsilon, \mathbf{v}^\varepsilon) &= \frac{1}{2} (Q(\mathbf{v}^\varepsilon, \mathbf{v}^\varepsilon) + Q((\mathbf{v}^\varepsilon)^\perp, (\mathbf{v}^\varepsilon)^\perp)) \\ &\quad + \frac{1}{2} (Q(\mathbf{v}^\varepsilon, \mathbf{v}^\varepsilon) - Q((\mathbf{v}^\varepsilon)^\perp, (\mathbf{v}^\varepsilon)^\perp)) \\ &= \text{Tr}(Q) e(\mathbf{v}^\varepsilon) - \varepsilon \frac{d}{dt} \left(\frac{1}{2} \Re(Q)(\mathbf{v}^\varepsilon, (\mathbf{v}^\varepsilon)^\perp) \right) \end{aligned}$$

where

$$e(\mathbf{v}^\varepsilon) := \frac{1}{2} \|\mathbf{v}^\varepsilon\|^2.$$

Inhomogeneous magnetic field, large time.

Proposition

$$\|(\mathbf{x}^\varepsilon, \frac{1}{2}\|v_\varepsilon\|^2)(t) - (\mathbf{y}^\varepsilon, e^\varepsilon)(t)\| \leq \varepsilon C_{\varepsilon t, \|\mathbf{v}^\varepsilon(0)\|, \varepsilon, \|E^\varepsilon\|_{W^{2,\infty}}, \|\frac{1}{B^\varepsilon}\|_{W^{1,\infty}}}$$

where $(\mathbf{y}^\varepsilon, e^\varepsilon)$ solves $(\mathbf{y}^\varepsilon, e^\varepsilon)(0) = (\mathbf{x}^\varepsilon, \frac{1}{2}\|v_\varepsilon\|^2)(0)$ and

$$\begin{cases} \frac{1}{\varepsilon} \frac{d\mathbf{y}^\varepsilon}{dt}(t) &= -\frac{(\mathbf{E}^\varepsilon)^\perp}{B^\varepsilon}(t, \mathbf{y}^\varepsilon(t)) - e^\varepsilon(t) \nabla_{\mathbf{x}}^\perp \left(\frac{1}{B^\varepsilon} \right)(t, \mathbf{y}^\varepsilon(t)) \\ \frac{1}{\varepsilon} \frac{de^\varepsilon}{dt}(t) &= e^\varepsilon(t) \operatorname{div}_{\mathbf{x}} \left(\frac{(\mathbf{E}^\varepsilon)^\perp}{B^\varepsilon} \right)(t, \mathbf{y}^\varepsilon(t)) \end{cases} .$$

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Remark 1. When B^ε is constant, the equation on \mathbf{y}^ε uncouples and if moreover \mathbf{E} is curl-free, $\frac{de^\varepsilon}{dt} \equiv 0$.

Inhomogeneous magnetic field, large time.

Proposition

$$\left\| \left(\mathbf{x}^\varepsilon, \frac{1}{2} \|v_\varepsilon\|^2 \right) (t) - \left(\mathbf{y}^\varepsilon, e^\varepsilon \right) (t) \right\| \leq \varepsilon C_{\varepsilon t, \|v^\varepsilon(0)\|, \varepsilon, \|E^\varepsilon\|_{W^{2,\infty}}, \left\| \frac{1}{B^\varepsilon} \right\|_{W^{1,\infty}}}$$

where $(\mathbf{y}^\varepsilon, e^\varepsilon)$ solves $(\mathbf{y}^\varepsilon, e^\varepsilon)(0) = (\mathbf{x}^\varepsilon, \frac{1}{2} \|v_\varepsilon\|^2)(0)$ and

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Remark 1. When B^ε is constant, the equation on \mathbf{y}^ε uncouples and if moreover \mathbf{E} is curl-free, $\frac{de^\varepsilon}{dt} \equiv 0$.

Remark 2.

$$\frac{d}{dt} \left(\frac{e^\varepsilon}{B^\varepsilon(\cdot, \mathbf{y}^\varepsilon)} \right) (t) = -\frac{e^\varepsilon(t)}{B^\varepsilon(t, \mathbf{y}^\varepsilon(t))^2} (\partial_t B^\varepsilon + \operatorname{curl}_{\mathbf{x}}(\mathbf{E}^\varepsilon))(t, \mathbf{y}^\varepsilon(t))$$

thus Faraday's law implies adiabatic invariance of $\mu^\varepsilon := e^\varepsilon / B^\varepsilon(\cdot, \mathbf{y}^\varepsilon)$.

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General magnetic fields.

Dropping ε -superscripts on fields...

$$\mathbf{B}(t, \mathbf{x}) = B(t, \mathbf{x}) \mathbf{e}_{\parallel}(t, \mathbf{x}), \quad B(t, \mathbf{x}) = \|\mathbf{B}(t, \mathbf{x})\|.$$

General magnetic fields.

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'Perp' operator

$$\mathbf{J}(t, \mathbf{x}) \mathbf{a} = \mathbf{a} \wedge \mathbf{e}_{\parallel}(t, \mathbf{x})$$

General magnetic fields.

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Decompositions

$$\begin{aligned} v_{\parallel}(t, \mathbf{x}, \mathbf{v}) &= \langle \mathbf{v}, \mathbf{e}_{\parallel}(t, \mathbf{x}) \rangle, \\ \mathbf{v}_{\perp}(t, \mathbf{x}, \mathbf{v}) &= \mathbf{v} - v_{\parallel}(t, \mathbf{x}, \mathbf{v}) \mathbf{e}_{\parallel}(t, \mathbf{x}), \\ e_{\perp}(t, \mathbf{x}, \mathbf{v}) &= \frac{1}{2} \|\mathbf{v}_{\perp}(t, \mathbf{x}, \mathbf{v})\|^2, \end{aligned}$$

$$\begin{aligned} E_{\parallel}(t, \mathbf{x}) &= \langle \mathbf{E}(t, \mathbf{x}), \mathbf{e}_{\parallel}(t, \mathbf{x}) \rangle, \\ \mathbf{E}_{\perp}(t, \mathbf{x}) &= \mathbf{E}(t, \mathbf{x}) - E_{\parallel}(t, \mathbf{x}) \mathbf{e}_{\parallel}(t, \mathbf{x}). \end{aligned}$$

Slow-fast identification.

$$\frac{dx^\varepsilon}{dt} = \mathbf{v}^\varepsilon, \quad \frac{d\mathbf{v}^\varepsilon}{dt} = \frac{B(\cdot, \mathbf{x}^\varepsilon)}{\varepsilon} \mathbf{J}(\cdot, \mathbf{x}^\varepsilon)(\mathbf{v}^\varepsilon) + \mathbf{E}(\cdot, \mathbf{x}^\varepsilon).$$

Slow-fast identification.

$$\frac{dx^\varepsilon}{dt} = v^\varepsilon, \quad \frac{dv^\varepsilon}{dt} = \frac{B(\cdot, x^\varepsilon)}{\varepsilon} \mathbf{J}(\cdot, x^\varepsilon)(v^\varepsilon) + \mathbf{E}(\cdot, x^\varepsilon).$$

Eliminating v_\perp

$$v_\perp(\cdot, x^\varepsilon, v^\varepsilon) = \varepsilon \frac{\mathbf{J} \mathbf{E}_\perp}{B}(\cdot, x^\varepsilon) - \varepsilon \frac{\mathbf{J}}{B}(\cdot, x^\varepsilon) \left(\frac{dv^\varepsilon}{dt} \right).$$

Slow-fast identification.

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Eliminating \mathbf{v}_\perp

$$\mathbf{v}_\perp(\cdot, \mathbf{x}^\varepsilon, \mathbf{v}^\varepsilon) = \varepsilon \frac{\mathbf{J}\mathbf{E}_\perp}{B}(\cdot, \mathbf{x}^\varepsilon) - \varepsilon \frac{\mathbf{J}}{B}(\cdot, \mathbf{x}^\varepsilon) \left(\frac{d\mathbf{v}^\varepsilon}{dt} \right).$$

Slow variables

$$\frac{d\mathbf{x}^\varepsilon}{dt} = \mathbf{v}^\varepsilon,$$

$$\frac{d\mathbf{v}_\parallel}{dt} = E_\parallel + \langle \mathbf{v}_\perp, \partial_t \mathbf{e}_\parallel + d_x \mathbf{e}_\parallel \mathbf{v}^\varepsilon \rangle,$$

$$\frac{d\mathbf{e}_\perp}{dt} = \langle \mathbf{E}_\perp - v_\parallel (\partial_t \mathbf{e}_\parallel + d_x \mathbf{e}_\parallel \mathbf{v}^\varepsilon), \mathbf{v}_\perp \rangle,$$

where **evaluations are dropped**.

General magnetic fields, first order.

Theorem (Filbet-LMR, *preprint* 2018.)

$(\mathbf{x}^\varepsilon, v_{\parallel}(\cdot, \mathbf{x}^\varepsilon, \mathbf{v}^\varepsilon), \mathbf{e}_{\perp}(\cdot, \mathbf{x}^\varepsilon, \mathbf{v}^\varepsilon))$ is $\mathcal{O}(\varepsilon)$ close to $\mathbf{Z}^\varepsilon = (\mathbf{y}^\varepsilon, v^\varepsilon, \mathbf{e}^\varepsilon)$ solving

$$\frac{d\mathbf{Z}^\varepsilon}{dt}(t) = \mathcal{V}_0(t, \mathbf{Z}^\varepsilon(t))$$

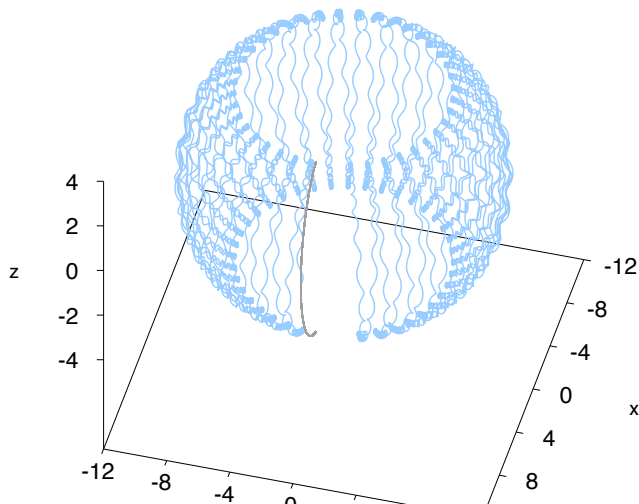
with the same initial datum, where

$$\mathcal{V}_0(t, \mathbf{Z}) = \begin{pmatrix} v \mathbf{e}_{\parallel}(t, \mathbf{y}) \\ E_{\parallel}(t, \mathbf{y}) + e \operatorname{div}_{\mathbf{x}} \mathbf{e}_{\parallel}(t, \mathbf{y}) \\ -v e \operatorname{div}_{\mathbf{x}} \mathbf{e}_{\parallel}(t, \mathbf{y}) \end{pmatrix}.$$

Spatial trajectory, failure of drifts.

Exact vs. first-order.

Reference trajectory : system (2.2) ———
First order model : system (2.6) ———



Drifts.

$$\mathbf{U}_{\mathbf{E} \times \mathbf{B}} := \frac{\mathbf{J} \mathbf{E}}{B},$$

$$\mathbf{U}_{\nabla B \times \mathbf{B}} := \mathbf{J} \nabla_{\mathbf{x}} \left(\frac{1}{B} \right),$$

$$\mathbf{U}_{\partial_t} := -\frac{\mathbf{J}}{B} \partial_t \mathbf{e}_{\parallel},$$

$$\mathbf{U}_{\text{curl} \mathbf{e}_{\parallel}} := \frac{1}{B} \langle \text{curl}_{\mathbf{x}} \mathbf{e}_{\parallel}, \mathbf{e}_{\parallel} \rangle \mathbf{e}_{\parallel},$$

$$\mathbf{U}_{\text{curv}} := -\frac{\mathbf{J}}{B} (d_{\mathbf{x}} \mathbf{e}_{\parallel} \mathbf{e}_{\parallel}),$$

$$\boldsymbol{\Sigma} = \mathbf{U}_{\partial_t} + \nu \mathbf{U}_{\text{curv}},$$

$$\mathbf{U}_{\text{drift}} = \mathbf{U}_{\mathbf{E} \times \mathbf{B}} + \nu \boldsymbol{\Sigma} + e (\mathbf{U}_{\text{curl} \mathbf{e}_{\parallel}} + \mathbf{U}_{\nabla B \times \mathbf{B}}).$$

Guiding-center variables.

$$\mathbf{x}_{\text{gc}}^\varepsilon(t, \mathbf{x}, \mathbf{v}) := \mathbf{x} + \varepsilon \frac{\mathbf{J}\mathbf{v}}{B}$$

$$v_{\text{gc}}^\varepsilon(t, \mathbf{x}, \mathbf{v}) := v_{\parallel} + \varepsilon \langle \mathbf{v}_{\perp}, \boldsymbol{\Sigma} \rangle + \frac{\varepsilon}{2B} \langle \mathbf{J}\mathbf{v}_{\perp}, \Re(d_{\mathbf{x}} \mathbf{e}_{\parallel}) \mathbf{v}_{\perp} \rangle$$

$$\begin{aligned} \mathbf{e}_{\text{gc}}^\varepsilon(t, \mathbf{x}, \mathbf{v}) &:= \mathbf{e}_{\perp} - \varepsilon \langle \mathbf{v}_{\perp}, \mathbf{U}_{\mathbf{E} \times \mathbf{B}} + v_{\parallel} \boldsymbol{\Sigma} \rangle \\ &\quad - \frac{\varepsilon v_{\parallel}}{2B} \langle \mathbf{J}\mathbf{v}_{\perp}, \Re(d_{\mathbf{x}} \mathbf{e}_{\parallel}) \mathbf{v}_{\perp} \rangle \end{aligned}$$

General magnetic fields, second order.

Theorem (Filbet-LMR, *preprint* 2018.)

$(\mathbf{x}_{\text{gc}}^\varepsilon, \mathbf{v}_{\text{gc}}(\cdot, \mathbf{x}^\varepsilon, \mathbf{v}^\varepsilon), \mathbf{e}_{\text{gc}}(\cdot, \mathbf{x}^\varepsilon, \mathbf{v}^\varepsilon))$ is $\mathcal{O}(\varepsilon^2)$ close to $\mathbf{Z}_{\text{gc}}^\varepsilon$ solving

$$\frac{d\mathbf{Z}_{\text{gc}}^\varepsilon}{dt}(t) = (\mathcal{V}_0 + \varepsilon \mathcal{V}_1)(t, \mathbf{Z}_{\text{gc}}^\varepsilon(t))$$

with the same initial datum, where

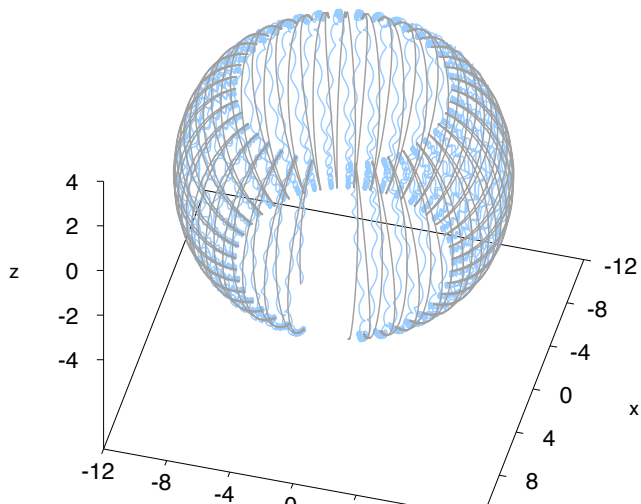
$$\mathcal{V}_1 = \begin{pmatrix} \mathbf{U}_{\text{drift}} \\ \langle \boldsymbol{\Sigma}, \mathbf{E} \rangle + e \operatorname{div}_{\mathbf{x}} \boldsymbol{\Sigma} \\ -e [\langle \mathbf{U}_{\text{curv}}, \mathbf{E} \rangle + \operatorname{div}_{\mathbf{x}} (\mathbf{U}_{\mathbf{E} \times \mathbf{B}} + \nu \boldsymbol{\Sigma})] \end{pmatrix}.$$

For an example of **large time**, see also Filbet-LMR, *preprint* 2018.

Illustration: spatial trajectory.

Exact vs. second-order.

Reference trajectory : system (2.2) ————
Second order model : system (2.16) ————



Outline.

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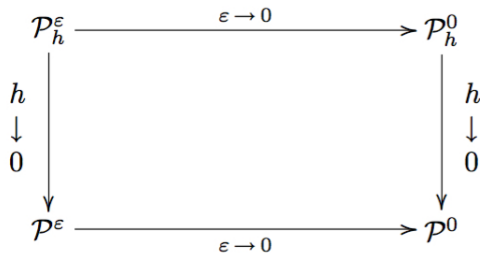
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Preserving asymptotics.

h discretization parameter.

ε asymptotic parameter.



Goals.

Main goals

- $\mathcal{P}_h^\varepsilon \rightarrow \mathcal{P}_h^0$ uniformly in h :
compute **slow dynamics** even with a low resolution.

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- **Non invasive** and **robust**.
- **Higher-order**.

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- **Non invasive** and **robust**.
- **Higher-order**.

Similar goals in

Frénod-Hirstoaga-Lutz-Sonnendrücker, *Commun. Comput. Phys.* 2015.

Computation of a few oscillation phases in

Crouseilles-Lemou-Méhats, *JCP* 2013.

Particle-in-cell methods.

Fix a **time step** Δt . For some $m \in \mathbf{N}^*$, f_0 approximated by

$$f_m^0 = \sum_{k=0}^m \omega_k^m \delta \mathbf{x}_m^k .$$

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Then, for $n \in \mathbf{N}$,

$$f_\varepsilon^{n,\Delta t,m} := (\Phi_\varepsilon^{n,\Delta t,m})_*(f_m^0) = \sum_{k=0}^m \omega_k^m \delta_{\Phi_\varepsilon^{n,\Delta t,m}(\mathbf{x}_m^k)}.$$

where $\Phi_\varepsilon^{n,\Delta t,m}$ is a **discrete flow** approximating $\Phi^\varepsilon(n\Delta t, 0, \cdot)$.

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Remark. For nonlinear PDEs, everything is computed altogether and Dirac masses are smoothed.

For **Vlasov-Poisson**, see **Filbet-LMR**, *SIAM Num. Anal.* 2016

and **Filbet-LMR**, *SIAM Num. Anal.* 2017.

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Long time variables and slow fields.

From now on, we restrict to **dimension two** and **large time** asymptotics.

Long time variables and slow fields.

From now on, we restrict to **dimension two** and **large time** asymptotics.

For the sake of clarity, we replace t with εt

$$\begin{aligned}\varepsilon \frac{dx^\varepsilon}{dt}(t) &= \mathbf{v}^\varepsilon(t) \\ \varepsilon \frac{dv^\varepsilon}{dt}(t) &= -\frac{B(t, \mathbf{x}^\varepsilon(t))}{\varepsilon} (\mathbf{v}^\varepsilon(t))^\perp + \mathbf{E}(t, \mathbf{x}^\varepsilon(t))\end{aligned}$$

hence **implicitly** assuming **slow fields**.

Homogeneous case: a first-order scheme.

$(\Phi_\varepsilon^{n,\Delta t}(\mathbf{x}_\varepsilon^0, \mathbf{v}_\varepsilon^0))_{n \in \mathbf{N}}$ computed through

$$\frac{\mathbf{x}_\varepsilon^{n+1,\Delta t} - \mathbf{x}_\varepsilon^{n,\Delta t}}{\Delta t} = \frac{\mathbf{v}_\varepsilon^{n+1,\Delta t}}{\varepsilon},$$
$$\frac{\mathbf{v}_\varepsilon^{n+1,\Delta t} - \mathbf{v}_\varepsilon^{n,\Delta t}}{\Delta t} = \frac{1}{\varepsilon} \left(-\frac{(\mathbf{v}_\varepsilon^{n+1,\Delta t})^\perp}{\varepsilon} + \mathbf{E}(t_{\Delta t}^n, \mathbf{x}_\varepsilon^{n,\Delta t}) \right).$$

where $t_{\Delta t}^n = n\Delta t$.

Inspired by [Boscarino-Filbet-Russo](#), *J. Sci. Comput.* 2016
on dissipative problems.

Homogeneous case: a first-order scheme.

$(\Phi_\varepsilon^{n,\Delta t}(\mathbf{x}_\varepsilon^0, \mathbf{v}_\varepsilon^0))_{n \in \mathbf{N}}$ computed through

$$\begin{aligned}\frac{\mathbf{x}^{n+1} - \mathbf{x}^n}{\Delta t} &= \frac{\mathbf{v}^{n+1}}{\varepsilon}, \\ \frac{\mathbf{v}^{n+1} - \mathbf{v}^n}{\Delta t} &= \frac{1}{\varepsilon} \left(-\frac{(\mathbf{v}^{n+1})^\perp}{\varepsilon} + \mathbf{E}(t^n, \mathbf{x}^n) \right).\end{aligned}$$

where $t^n = n\Delta t$.

Implicit dependences on ε and Δt .

Inspired by [Boscarino-Filbet-Russo](#), *J. Sci. Comput.* 2016
on dissipative problems.

Consistency when $\varepsilon \rightarrow 0$ at fixed Δt .

Proposition (Filbet-LMR, *SIAM Num. Anal.* 2016.)

Fix $\Delta t > 0$. Assume

- for any $n \in \mathbf{N}$, $\varepsilon^2 \mathbf{x}_\varepsilon^n \xrightarrow{\varepsilon \rightarrow 0} 0$;
- $(\mathbf{x}_\varepsilon^0, \varepsilon \mathbf{v}_\varepsilon^0) \xrightarrow{\varepsilon \rightarrow 0} (\mathbf{y}^0, 0)$.

Then, for any n , there exists \mathbf{y}^n such that

$$\mathbf{x}_\varepsilon^n \xrightarrow{\varepsilon \rightarrow 0} \mathbf{y}^n.$$

Limiting sequence satisfies

$$\frac{\mathbf{y}^{n+1} - \mathbf{y}^n}{\Delta t} = -\mathbf{E}(t^n, \mathbf{y}^n)^\perp.$$

From now on, fixed initial data.

Convergence analysis, spatial variable.

Proposition (Filbet-LMR-Zakerzadeh, *work in progress.*)

$$\|\mathbf{x}^\varepsilon(t^n) - \mathbf{y}(t_n)\| = \mathcal{O}(\varepsilon), \quad ,$$

$$\|\mathbf{y}(t^n) - \mathbf{y}^n\| = \mathcal{O}(\Delta t),$$

Convergence analysis, spatial variable.

Proposition (Filbet-LMR-Zakerzadeh, *work in progress.*)

$$\begin{aligned}\|\mathbf{x}^\varepsilon(t^n) - \mathbf{y}(t_n)\| &= \mathcal{O}(\varepsilon), & \|\mathbf{x}_\varepsilon^n - \mathbf{y}^n\| &= \mathcal{O}(\varepsilon), \\ \|\mathbf{y}(t^n) - \mathbf{y}^n\| &= \mathcal{O}(\Delta t), & \|\mathbf{x}_\varepsilon^n - \mathbf{x}^\varepsilon(t_n)\| &= \mathcal{O}\left(\min\left(\left\{\Delta t + \varepsilon, \frac{\Delta t}{\varepsilon^3}\right\}\right)\right).\end{aligned}$$

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Thus

$$\|\mathbf{x}_\varepsilon^n - \mathbf{x}^\varepsilon(t_n)\| = \begin{cases} \mathcal{O}(\Delta t) & \text{when } \varepsilon \leq \Delta t \\ \mathcal{O}(\varepsilon) & \text{when } \varepsilon^4 \leq \Delta t \leq \varepsilon \\ \mathcal{O}\left(\frac{\Delta t}{\varepsilon^3}\right) & \text{when } \Delta t \leq \varepsilon^4 \end{cases}$$

and in particular $\|\mathbf{x}_\varepsilon^n - \mathbf{x}^\varepsilon(t_n)\| = \mathcal{O}((\Delta t)^{\frac{1}{4}})$.

Convergence analysis, guiding center.

Proposition (Filbet-LMR-Zakerzadeh, *work in progress.*)

$$\|\mathbf{x}_{\text{gc}}^\varepsilon(t^n) - \mathbf{y}_{\text{gc}}^\varepsilon(t_n)\| = \mathcal{O}(\varepsilon^2),$$

,

$$\|\mathbf{y}_{\text{gc}}^\varepsilon(t^n) - (\mathbf{y}_{\text{gc}})_\varepsilon^n\| = \mathcal{O}(\Delta t),$$

Convergence analysis, guiding center.

Proposition (Filbet-LMR-Zakerzadeh, *work in progress.*)

$$\|\mathbf{x}_{\text{gc}}^\varepsilon(t^n) - \mathbf{y}_{\text{gc}}^\varepsilon(t_n)\| = \mathcal{O}(\varepsilon^2),$$

$$\|(\mathbf{x}_{\text{gc}}^\varepsilon)^n - (\mathbf{y}_{\text{gc}}^\varepsilon)^n\| = \mathcal{O}(\varepsilon^2 + \Delta t \varepsilon),$$

$$\|\mathbf{y}_{\text{gc}}^\varepsilon(t^n) - (\mathbf{y}_{\text{gc}}^\varepsilon)^n\| = \mathcal{O}(\Delta t),$$

$$\|(\mathbf{x}_{\text{gc}}^\varepsilon)^n - \mathbf{x}_{\text{gc}}^\varepsilon(t_n)\| = \mathcal{O}\left(\min\left(\left\{\Delta t + \varepsilon^2, \frac{\Delta t}{\varepsilon^3}\right\}\right)\right).$$

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$$\|\mathbf{y}_{\text{gc}}^\varepsilon(t^n) - (\mathbf{y}_{\text{gc}}^\varepsilon)^n\| = \mathcal{O}(\Delta t),$$

$$\|(\mathbf{x}_{\text{gc}}^\varepsilon)^n - \mathbf{x}_{\text{gc}}^\varepsilon(t_n)\| = \mathcal{O}\left(\min\left(\left\{\Delta t + \varepsilon^2, \frac{\Delta t}{\varepsilon^3}\right\}\right)\right).$$

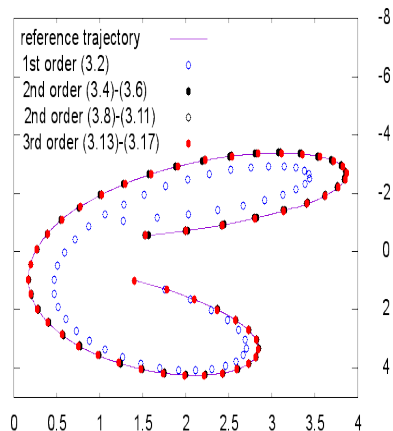
Thus

$$\|(\mathbf{x}_{\text{gc}}^\varepsilon)^n - \mathbf{x}_{\text{gc}}^\varepsilon(t_n)\| = \begin{cases} \mathcal{O}(\Delta t) & \text{when } \varepsilon^2 \leq \Delta t \\ \mathcal{O}(\varepsilon^2) & \text{when } \varepsilon^5 \leq \Delta t \leq \varepsilon^2 \\ \mathcal{O}\left(\frac{\Delta t}{\varepsilon^3}\right) & \text{when } \Delta t \leq \varepsilon^5 \end{cases}$$

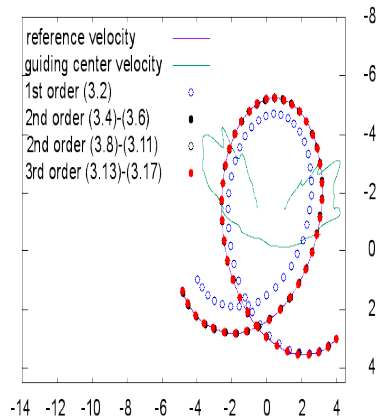
and in particular $\|(\mathbf{x}_{\text{gc}}^\varepsilon)^n - \mathbf{x}_{\text{gc}}^\varepsilon(t_n)\| = \mathcal{O}((\Delta t)^{\frac{2}{5}})$.

Phase space, $\varepsilon = 0.1$.

(a) spatial trajectory,

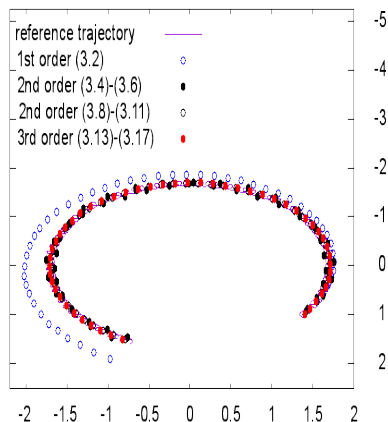


(b) velocity trajectory.

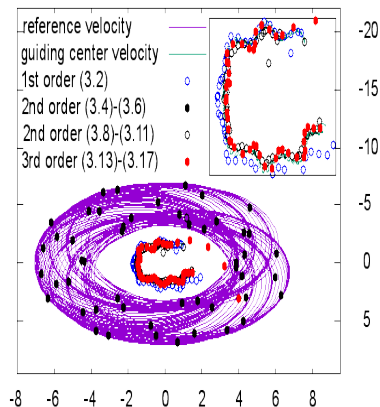


Phase space, $\varepsilon = 0.01$.

(a) spatial trajectory,

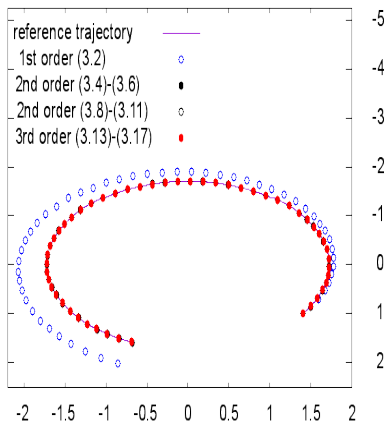


(b) velocity trajectory.

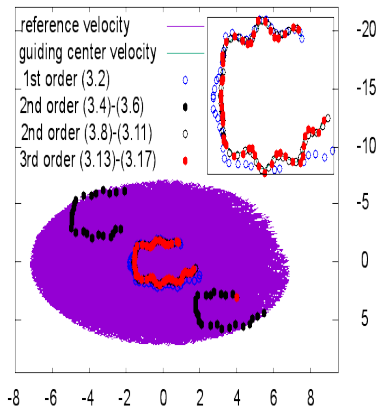


Phase space, $\varepsilon = 0.001$.

(a) spatial trajectory,



(b) velocity trajectory.



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Continuous systems.

$$\begin{cases} \varepsilon \frac{dx^\varepsilon}{dt} = \mathbf{v}^\varepsilon \\ \varepsilon \frac{dv^\varepsilon}{dt} = -\frac{B(t, \mathbf{x}^\varepsilon(t))}{\varepsilon} (\mathbf{v}^\varepsilon)^\perp + \mathbf{E}(t, \mathbf{x}^\varepsilon(t)) \end{cases}$$

$(\mathbf{x}^\varepsilon, \frac{1}{2}\|\mathbf{v}^\varepsilon\|^2)$ converges to (\mathbf{y}, e) such that

$$\begin{cases} \frac{dy}{dt}(t) = -\frac{\mathbf{E}^\perp}{B}(t, \mathbf{y}(t)) - e(t) \nabla_{\mathbf{x}}^\perp \left(\frac{1}{B} \right) (t, \mathbf{y}(t)) \\ \frac{de}{dt}(t) = e(t) \operatorname{div}_{\mathbf{x}} \left(\frac{\mathbf{E}^\perp}{B} \right) (t, \mathbf{y}(t)) \end{cases}$$

Issue

How to get \mathbf{v}^ε go to 0 weakly and $\|\mathbf{v}^\varepsilon\|^2$ go to $2e$ strongly at discrete level ?

Augmented version.

An answer. Discretize

$$\left\{ \begin{array}{l} \varepsilon \frac{dx^\varepsilon}{dt} = \mathbf{w}^\varepsilon \\ \varepsilon \frac{de^\varepsilon}{dt} = \langle \mathbf{E}, \mathbf{w}^\varepsilon \rangle \\ \varepsilon \frac{d\mathbf{w}^\varepsilon}{dt} = \frac{B}{\varepsilon} (\mathbf{w}^\varepsilon)^\perp + \mathbf{E} \end{array} \right.$$

and recover \mathbf{v}^ε by

$$\mathbf{v}^\varepsilon = \sqrt{2}e^\varepsilon \frac{\mathbf{w}^\varepsilon}{\|\mathbf{w}^\varepsilon\|}.$$

Augmented version.

An answer. Discretize

$$\left\{ \begin{array}{l} \varepsilon \frac{dx^\varepsilon}{dt} = \mathbf{w}^\varepsilon \\ \varepsilon \frac{de^\varepsilon}{dt} = \langle \mathbf{E}, \mathbf{w}^\varepsilon \rangle \\ \varepsilon \frac{d\mathbf{w}^\varepsilon}{dt} = \frac{B}{\varepsilon} (\mathbf{w}^\varepsilon)^\perp + \mathbf{E} - \chi(e^\varepsilon, \mathbf{w}^\varepsilon) \nabla_x(\ln(B)) \end{array} \right.$$

and recover \mathbf{v}^ε by

$$\mathbf{v}^\varepsilon = \sqrt{2} e^\varepsilon \frac{\mathbf{w}^\varepsilon}{\|\mathbf{w}^\varepsilon\|}.$$

χ chosen so that

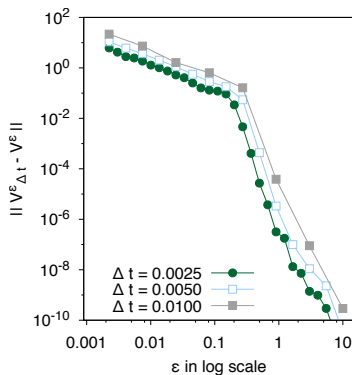
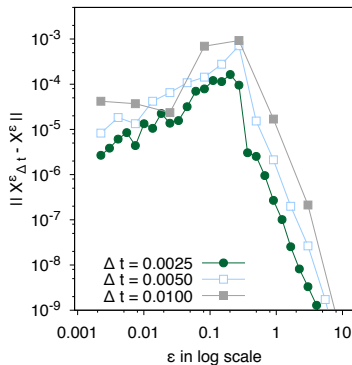
$$\chi\left(\frac{1}{2}\|\mathbf{w}\|^2, \mathbf{w}\right) = 0, \quad \lim_{\mathbf{w} \rightarrow 0} \chi(e, \mathbf{w}) = e.$$

See [Filbet-LMR](#), *SIAM Num. Anal.* 2017.

Accuracy.

Errors (a) $\|\mathbf{x}_\varepsilon^{\Delta t} - \mathbf{x}^\varepsilon\|$,

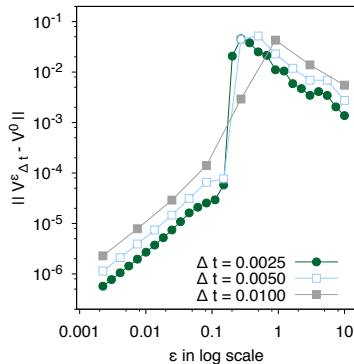
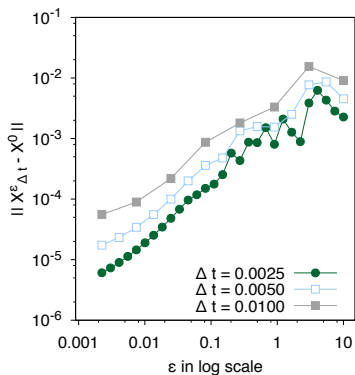
(b) $\|\mathbf{v}_\varepsilon^{\Delta t} - \mathbf{v}^\varepsilon\|$ for a third order scheme.



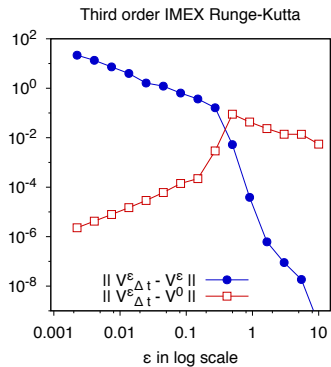
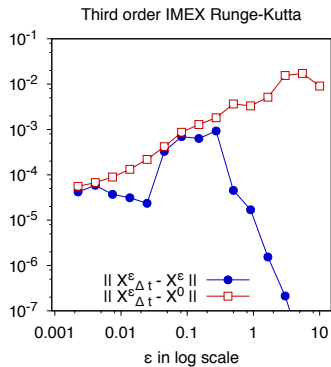
Asymptotics.

Errors (a) $\|\mathbf{x}_\varepsilon^{\Delta t} - \mathbf{y}\|$,

(b) $\|\mathbf{v}_\varepsilon^{\Delta t} - \mathbf{v}\|$ for a third order scheme.



Transitions.



Superimposed comparisons.

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References. Filbet-LMR,

- *Asymptotically stable PIC methods for the VP system with strong external magnetic field. SIAM Num. Anal.* 2016.
- *Asymptotically preserving particle-in-cell methods for inhomogeneous strongly magnetized plasmas. SIAM Num. Anal.* 2017.
- *Asymptotics of the three dimensional Vlasov equation in the large magnetic field limit. preprint* 2018.
- *Convergence analysis of asymptotically preserving schemes for strongly magnetized plasmas. Work in progress.* With Zakerzadeh

Analytic prospects.

- **Large time complex 3-D geometries.**
- **Nonlinear fields.**
- Interaction with **evanescent collisions**. See work with Herda.

Numerical prospects.

- **Complex 3-D geometries.**